

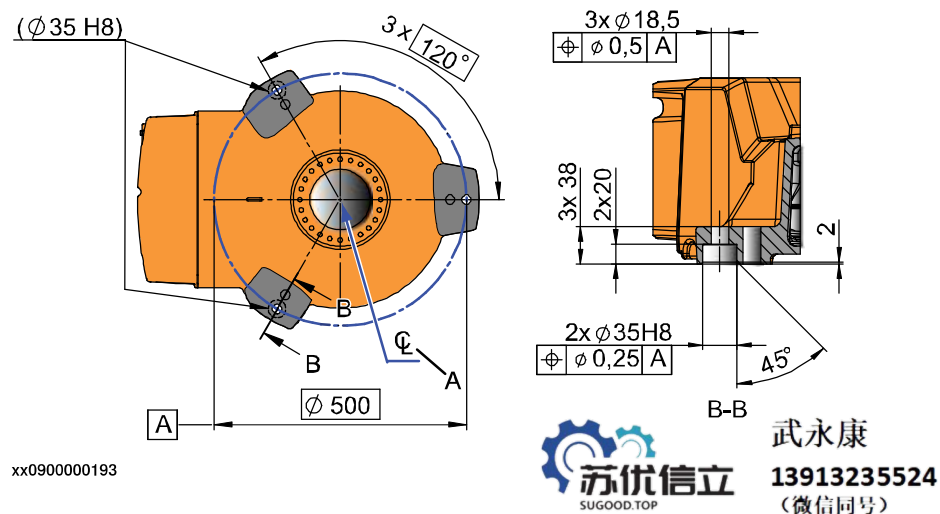
1 Description

1.3.3 Mounting the manipulator

Continued

Fastening holes robot base

Only 3 screws ($\varnothing 500$) are required for fastening the robot.



Attachment bolts, specification

The table below specifies required bolts and washers for securing the robot at installation site

Specification	Description
Attachment bolts, 3 pcs	M16 x 60 (installation directly on foundation) M16 x 70/80 (installation on foundation or base plate, using guiding sleeves)
Washers, 3 pcs	17 x 30 x 3
Quality	Quality 8.8
Tightening torque	200 Nm



Note

For best AbsAcc performance, use the guide holes according to the preceding figure.

Mounting surface and bushings



Note

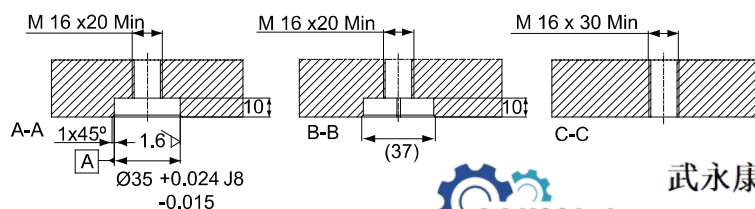
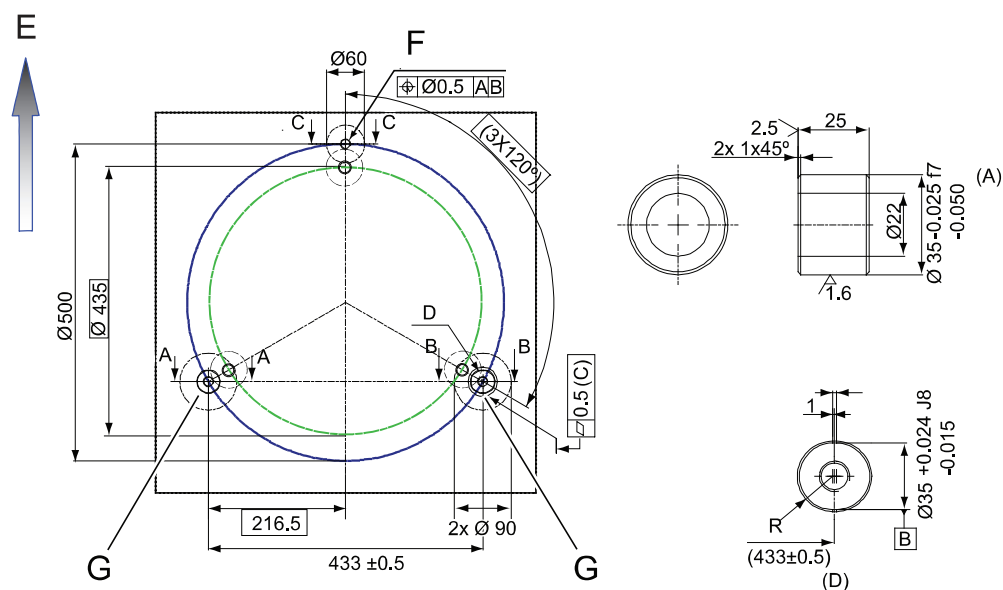
Only the three outer holes are used to secure the robot!

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1 Description

1.3.3 Mounting the manipulator

Continued



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Pos	Description
(C)	3x common zone
E	Position of the front of the robot
F	1xM16, depth 30 minimum
G	Guide sleeves (2 pcs)